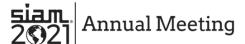
Efficient Convergent Boundary Integral Methods for Slender Bodies

Dhairya Malhotra, Alex Barnett

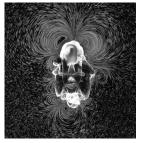


July 19, 2021

Motivations



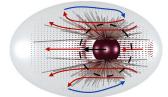
Stokes simulations with fibers are key to modeling complex fluids (suspensions, rheology, industrial, biomedical, cellular biophysics).



Starfish larvae (Gilpin et al. 2016)



Drosophila oocyte (Stein et al. 2021)



Mitotic spindle (Nazockdast et al. 2015)

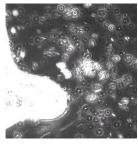
Motivations



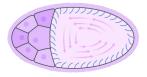
Stokes simulations with fibers are key to modeling complex fluids (suspensions, rheology, industrial, biomedical, cellular biophysics).

Slender Body Theory (SBT):

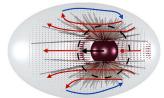
- Asymptotic expansion in radius (r) as r o 0 (Keller-Rubinow '76).
- Doublet correction to make velocity theta-independent (Johnson '80).



Starfish larvae (Gilpin et al. 2016)



Drosophila oocyte (Stein et al. 2021)



Mitotic spindle (Nazockdast et al. 2015)

Slender Body Theory



Error estimates: Rigorous analysis difficult (few very recent studies)

- ullet classical asymptotics claims: $r^2 \log(r)$
- ullet rigorous analysis: $r \log^{3/2}(r)$ (Mori-Ohm-Spirn '19)
- numerical tests: $r^{1.7}$ (Mitchell et al. '21 -- verify close-touching breakdown) close-to-touching with gap=10r, only 2.5-digits in the infty-norm. r=1e-2 only 1-2 digits achievable by SBT.

Limitations:

- no convergence analysis for fibers of given nonzero radius.
- uncontrolled errors when fibers close O(r).

Efficient convergent BIE method needed, allowing adaptivity for close interactions.

Goals



Solve the slender body BVP

- in a convergent way.
- adaptively when fibers become close.
- efficiently with effort independent of varying radius.

Validate current SBT simulations.

Most existing quadratures cannot resolve high aspect ratio geometries.

Related work: Mitchell et al, '21

mixed-BVP corresponding to flexible fiber loop

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Solve the slender body BVP

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mixed-BVP corresponding to flexible fiber loop

We focus on the static BVP for rigid fibers

mobility problems (rigid and flexible fiber) for future.

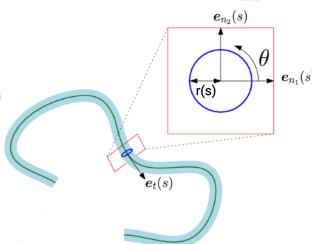
Only loops for now, to avoids complications with endpoint singularities.

Discretization



Geometry description:

- ullet parameterization s along fiber length
- ullet coordinates x(s) of centerline curve
- ullet circular cross-section with radius r(s)
- ullet orientation vector $e_{n_1}(s)$



Discretization

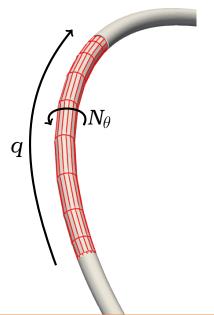


Geometry description:

- ullet parameterization s along fiber length
- ullet coordinates x(s) of centerline curve
- ullet circular cross-section with radius r(s)
- ullet orientation vector $e_{n_1}(s)$

Discretization:

- ullet piecewise Chebyshev (order q) discretization in s for x(s), r(s) and $e_{n_1}(s)$
- Collocation nodes: tensor product of Chebyshev and Fourier discretization in angle with order N_{θ} .





$$u(x) = \int_{\Gamma} \mathcal{K}(x-y) \; \sigma(y) \; da(y) = \sum_{k=1}^{N_{panel}} \int_{\gamma_k} \mathcal{K}(x-y) \; \sigma(y) \; da(y)$$



$$\begin{split} u(x) &= \int_{\Gamma} \mathcal{K}(x-y) \; \sigma(y) \; da(y) \; = \sum_{k=1}^{N_{panel}} \int_{\gamma_k} \mathcal{K}(x-y) \; \sigma(y) \; da(y) \\ &= \underbrace{\sum_{x \notin \mathcal{N}(\gamma_k)} \int_{\gamma_k} \mathcal{K}(x-y) \; \sigma(y) \; da(y)}_{\text{far-field}} \; + \underbrace{\sum_{x \in \mathcal{N}(\gamma_k)} \int_{\gamma_k} \mathcal{K}(x-y) \; \sigma(y) \; da(y)}_{\text{near interactions}} \end{split}$$



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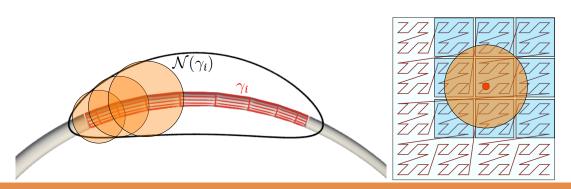
Far field approximation:

$$\int_{\gamma_k} \mathcal{K}(x-y) \; \sigma(y) \; da(y) \; \approx \; \sum_{i,j} \frac{2\pi w_i}{N_\theta} \mathcal{K}(x-y(s_i,\theta_j)) \; \sigma(s_i,\theta_j) \; J(s_i,\theta_j)$$

- Gauss-Legendre quadrature (s_i, w_i) of order q.
- periodic trapezoidal quadrature of order N_{θ} in θ .
- ullet given tolerance ϵ , define region $\mathcal{N}(\gamma_k)$, such that far-field is valid outside it.



$$\begin{split} u(x) &= \int_{\Gamma} \mathcal{K}(x-y) \ \sigma(y) \ da(y) = \sum_{k=1}^{N_{panel}} \int_{\gamma_k} \mathcal{K}(x-y) \ \sigma(y) \ da(y) \\ &= \underbrace{\sum_{x \notin \mathcal{N}(\gamma_k)} \int_{\gamma_k} \mathcal{K}(x-y) \ \sigma(y) \ da(y)}_{\text{far-field}} + \underbrace{\sum_{x \in \mathcal{N}(\gamma_k)} \int_{\gamma_k} \mathcal{K}(x-y) \ \sigma(y) \ da(y)}_{\text{near interactions}} \end{split}$$





Near interactions: for $x \in \mathcal{N}(\gamma_k)$

$$\int_{\gamma_k} \mathcal{K}(x-y) \ \sigma(y) \ da(y) \ = \ \int_{s} \int_{\theta} \mathcal{K}(x-y(s,\theta)) \ \sigma(s,\theta) \ J(s,\theta) \ d\theta \ ds$$

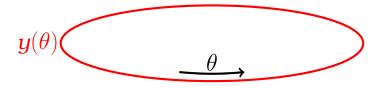
Inner integral:

- potential from a ring source (modal or toroidal Green's function).
- ullet can be nearly singular as $s\longrightarrow s_0$.

Outer integral:

- singular if $x \in \gamma_k$ with logarithmic singularity at $s = s_0$.
- ullet $1/s^lpha$ decay as $|s-s_0| \longrightarrow \infty$



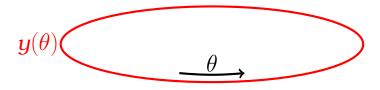


$$\int_{\theta} \mathcal{K}(x - y(\theta)) \ \sigma(\theta) \ d\theta = \sum_{n} \mathcal{K}_{n}(x) \widehat{\sigma_{n}}$$

where, $y(\theta)$ is a circular source loop, and $\mathcal{K}_n(x)=\int_{\theta}e^{-in\theta}\mathcal{K}(x-y(\theta))\;d\theta$ are the modal Green's functions.

• Periodic trapezoidal rule becomes expensive as $x \longrightarrow y$.



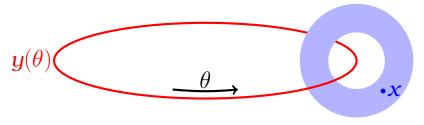


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where, $y(\theta)$ is a circular source loop, and $\mathcal{K}_n(x) = \int_{\theta} e^{-in\theta} \mathcal{K}(x - y(\theta)) \ d\theta$ are the modal Green's functions.

- Periodic trapezoidal rule becomes expensive as $x \longrightarrow y$.
- Fast evaluation using analytic representation in terms of special functions --Young, Hao, Martinsson JCP-2012;
 - method of choice for axisymmetric problems; however, assumes axisymmetric normal vector.



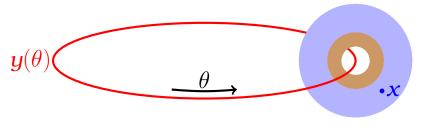


Build special quadrature rule (w_i, θ_i) for all $n \leq n_0$ and all targets x in the annulus:

$$\int_{\theta} e^{-in\theta} \mathcal{K}(x - y(\theta)) \ d\theta \approx \sum_{i} w_{i} e^{-in\theta_{i}} \mathcal{K}(x - y(\theta_{i}))$$

 inspired by generalized Gaussian quadratures of: Bremer, Gimbutas and Rokhlin - SISC 2010.



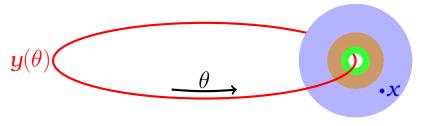


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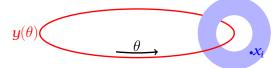
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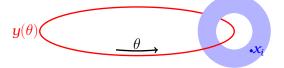
$$f_i(\theta) = e^{-in_i\theta} \mathcal{K}(x_i - y(\theta))$$





Generate several integrands:

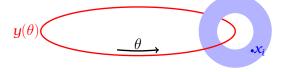
$$f_i(\theta) = e^{-in_i\theta} \mathcal{K}(x_i - y(\theta))$$



ullet Build an adaptive quadrature rule $(heta_j, w_j)$ to integrate products $f_i f_k$.



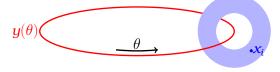
$$f_i(\theta) = e^{-in_i\theta} \mathcal{K}(x_i - y(\theta))$$



- ullet Build an adaptive quadrature rule $(heta_j, w_j)$ to integrate products $f_i f_k$.
- Set matrix $A_{ij} = f_i(\theta_j) \sqrt{w_j}$ and compute its truncated SVD: $A = U \Sigma V^*$.



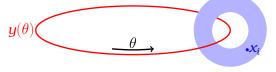
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- ullet Compute a column pivoted QR decomposition of V^* .



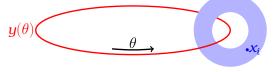
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- pprox 48 quadrature nodes for $n_0=8$ and 10-digits accuracy.
- pprox 13M (complex) modal Green's function evaluations/sec/core (Skylake 2.4GHz)



$$\int_{\gamma_k} \mathcal{K}(x-y) \ \sigma(y) \ da(y) \ = \ \int_{s} \ \left(\int_{\theta} \mathcal{K}(x-y(s,\theta)) \ \sigma(s,\theta) \ J(s,\theta) \ d\theta \right) \ ds$$

п



$$\int_{\gamma_k} \mathcal{K}(x-y) \ \sigma(y) \ da(y) \ = \ \int_{s} \ \left(\sum_{n=0}^{N_{ heta}/2-1} \mathcal{K}_n(x-y(s)) \ \widehat{\sigma_n}
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Near Interactions: x is off-surface or adjacent panel



П



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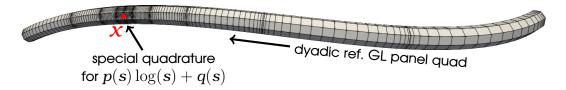
panel (Gauss-Lengendre) quadrature with dyadic refienement.

H

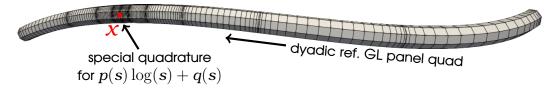








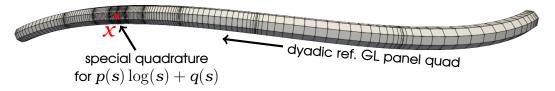




Special Quadrature Rules:

- replace composite panel quadratures with a single quadrature.
- integrand doesn't have closed form expression, but we can still generate quadrature rules!





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• Separate rules for different aspect ratios (1 - 10^4 in powers of 2)

Overall Algorithm



Discretization using piecewise polynomial approximation.

Far-field interactions using standard quadratures (GL \times PTR).

Near interactions

- fast scheme for modal Green's function.
- adaptive quadrature in s for non-singular case.
- generalized Chebyshev quadrature s for singular case.
- store local corrections to the far-field instead of computing on-the-fly.

Numerical Results

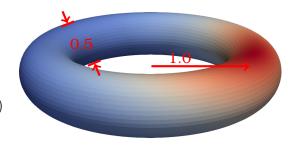
Numerical Results - comparison with BIEST



Green's identity (Laplace):

$$\Delta u = 0$$
, then for $x \in \Gamma$,

$$u(x) = \frac{u(x)}{2} + \mathcal{S}[\partial_n u](x) - \mathcal{D}[u](x)$$



Boundary Integral Equation Solver for Taylor States (BIEST)*

- quadrature for general toroidal surfaces with uniform grid.
- partition-of-unity to separate singular part of boundary integral.
- polar coordinate transform for singular integral.

^{*}JCP 2019 - Malhotra, Cerfon, Imbert-Gérard, O'Neil (https://github.com/dmalhotra/BIEST)

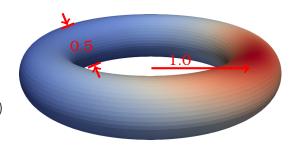
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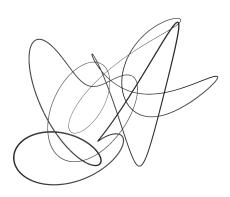


Sle	nder-body	/ Quadro	ature	BIEST*					
N	$\left\ \boldsymbol{e} \right\ _{\infty}$	T_{setup}	T_{eval}	N	$\left\ \boldsymbol{e} \right\ _{\infty}$	T_{setup}	T_{eval}		
320	1.5e-04	0.032	0.0004	507	2.0e-03	0.1319	0.0017		
720	3.5e-06	0.094	0.0013	1323	4.0e-06	1.4884	0.0042		
1280	5.4e-09	0.228	0.0033	2523	4.3e-09	6.6825	0.0313		
2000	2.5e-10	0.501	0.0079	4107	3.5e-10	15.4711	0.0862		

^{*}JCP 2019 - Malhotra, Cerfon, Imbert-Gérard, O'Neil (https://github.com/dmalhotra/BIEST)

Numerical Results

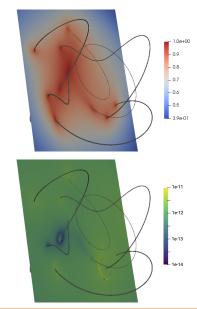




Exterior Laplace BVP:

$$\Delta u = 0, \quad u|_{\Gamma} = 1, \ u(x) \rightarrow 0 \text{ as } |x| \rightarrow 0$$

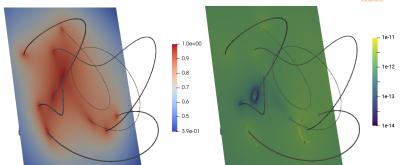
wire radius = 1.5e-3 to 4e-3 wire length = 16



Numerical Results - Laplace BVP



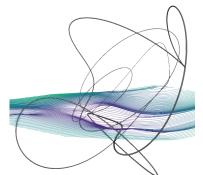
$$\begin{split} \Delta u &= 0 \\ u|_{\Gamma} &= 1 \\ u(x) &\to 0 \\ \text{as } |x| &\to 0 \end{split}$$

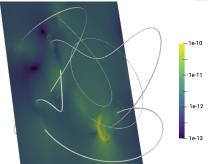


						1-core		40-cores		
N	N_{panel}	$N_{ heta}$	$\epsilon_{\rm GMRES}$	N _{iter}	$\left\ e \right\ _{\infty}$	T_{setup} (1	$N/T_{setup})$	T_{solve}	T_{setup}	T_{solve}
2.8e3	70	4	1e-02	4	4.2e-02	0.13	(2.1e4)	0.03	0.020	0.013
1.4e4	172	8	1e-04	10	1.0e-03	0.72	(1.9e4)	1.81	0.051	0.094
3.0e4	252	12	1e-05	14	3.1e-05	1.82	(1.6e4)	12.25	0.091	2.527
3.1e4	262	12	1e-07	20	2.4e-07	2.47	(1.2e4)	18.97	0.213	4.239
6.5e4	272	24	1e-09	28	1.1e-09	7.74	(8.4e3)	114.05	0.325	7.136

Numerical Results - Stokes BVP



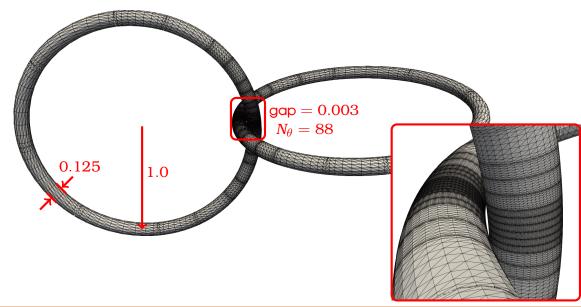




						1-core		40-cores		
N	N_{panel}	$N_{ heta}$	$\epsilon_{\rm GMRES}$	N _{iter}	$\left\ e \right\ _{\infty}$	T_{setup} (1	N/T_{setup}	T_{solve}	T_{setup}	T_{solve}
4.9e3	122	4	1e-03	10	1.9e-02	0.33	(1.4e4)	0.7	0.024	0.05
3.0e4	252	12	1e-05	21	1.7e-04	3.31	(9.1e3)	61.2	0.197	5.25
3.1e4	262	12	1e-07	33	4.1e-06	4.43	(7.0e3)	104.3	0.224	7.69
6.5e4	272	24	1e-09	43	1.4e-08	17.70	(3.6e3)	586.0	0.796	22.94
7.7e4	276	28	le-11	54	4.1e-09	27.67	(2.7e3)	1034.2	1.229	38.85

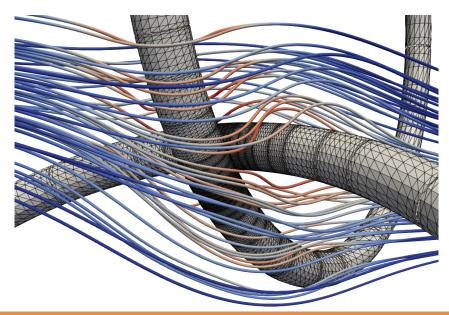
Numerical Results - close-to-touching





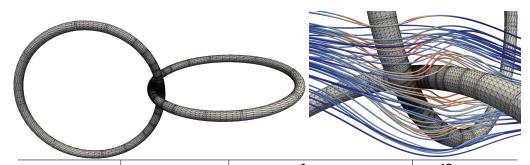
Numerical Results - close-to-touching





Numerical Results - close-to-touching





				1-core		40-cores		
N	$\epsilon_{\it GMRES}$	N _{iter}	$\left\ \boldsymbol{e} \right\ _{\infty}$	$T_{setup} (N/T_{setup})$	T_{solve}	T_{setup}	T_{solve}	
2.2e4	1e-02	4	2.1e-02	8.1 (2.7e+3)	6.5	1.28	1.4	
2.2e4	1e-05	24	2.4e-03	16.8 (1.3e+3)	42.9	2.50	7.7	
2.2e4	1e-07	43	2.8e-06	23.5 (9.2e+2)	81.6	3.31	12.8	
2.2e4	1e-10	59	5.4e-08	35.6 (6.0e+2)	122.9	4.06	19.2	
2.2e4	1e-13	72	1.3e-10	49.9 (4.3e+2)	162.6	5.27	23.2	

Conclusions



- Convergent boundary integral formulation for slender bodies.
 - unlike SBT, boundary conditions are actually enforced to high accuracy.
- ullet Special quadratures efficient for aspect ratios as large as 10^4 .
 - fast computation of modal/toroidal Green's function.
 - special (Chebyshev) quadratues for singular integrals along length of fibers.
 - quadrature setup rates up to 20,000 points/s/core for Laplace (comparable to FMM speeds).
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Ongoing work:

- Open fibers (singularities at ends).
- Mobility problem and flexible fibers.
- Comparison w/ SBT efficiency when SBT is sufficiently accurate.