

# Generalized Linear Models (GLM)

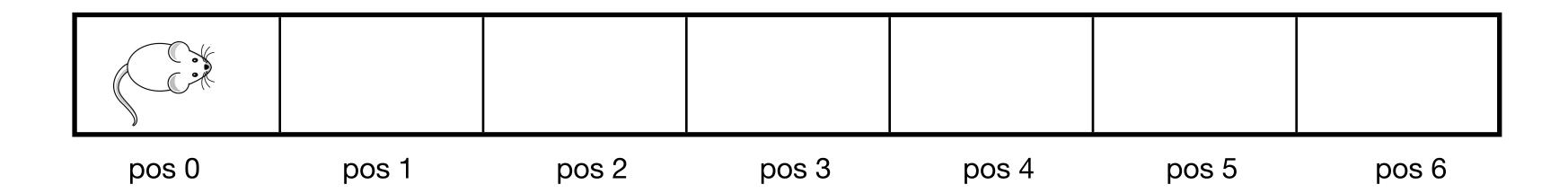
A conceptual introduction to GLM

# Roadmap

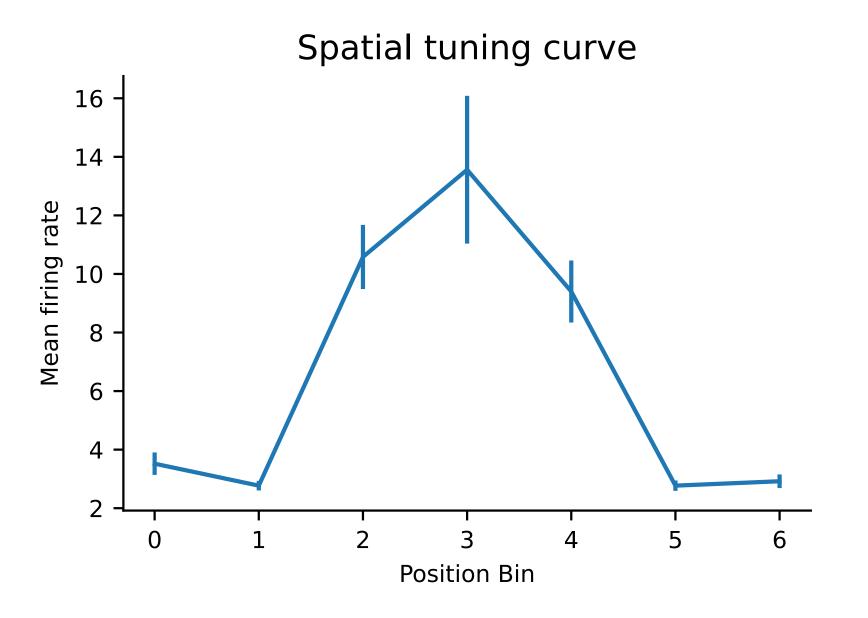
- Why models?
- What are GLMs?
- Why GLMs?
- What can I do with a GLM?
- GLMs In NeMoS
- What features can/should I use?
- Feature construction with Basis
- Summary
- Today's roadmap

# Why models? A hook

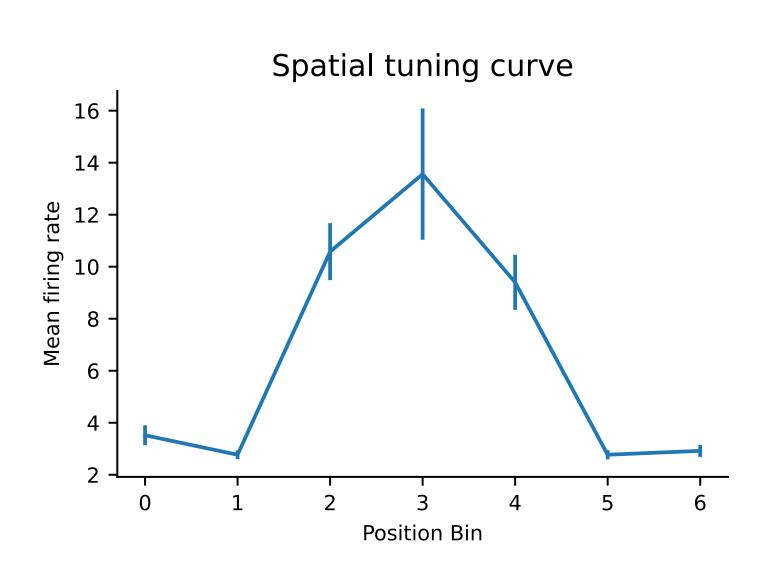
linear maze



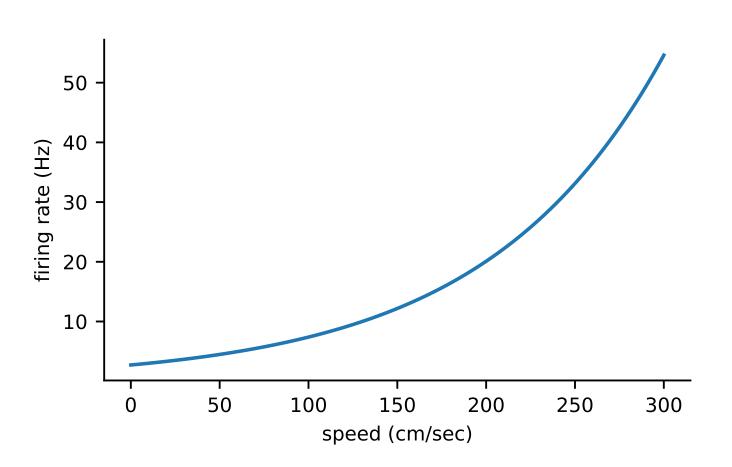
# is this neuron encoding the mouse position?



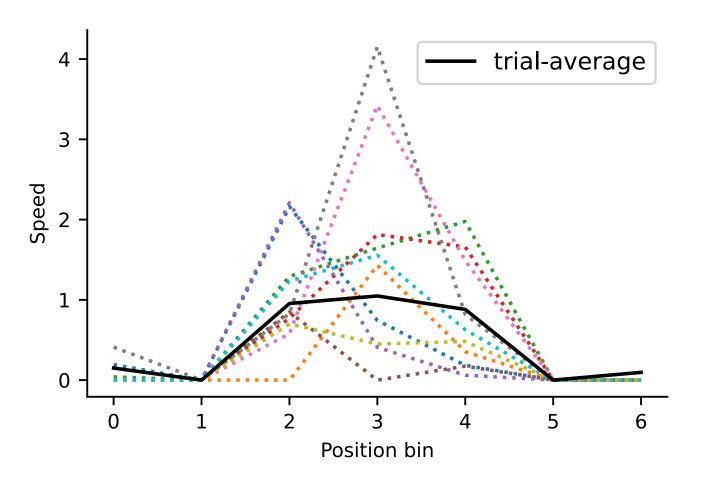
# Why models? A hook



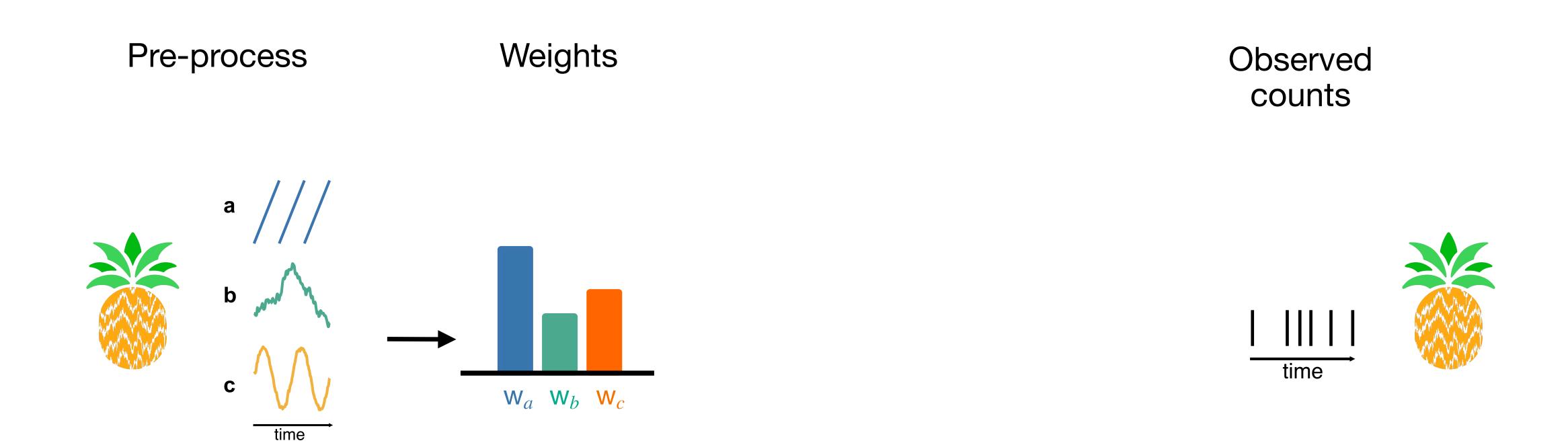
# ..actually, not!



# position and speed are correlated

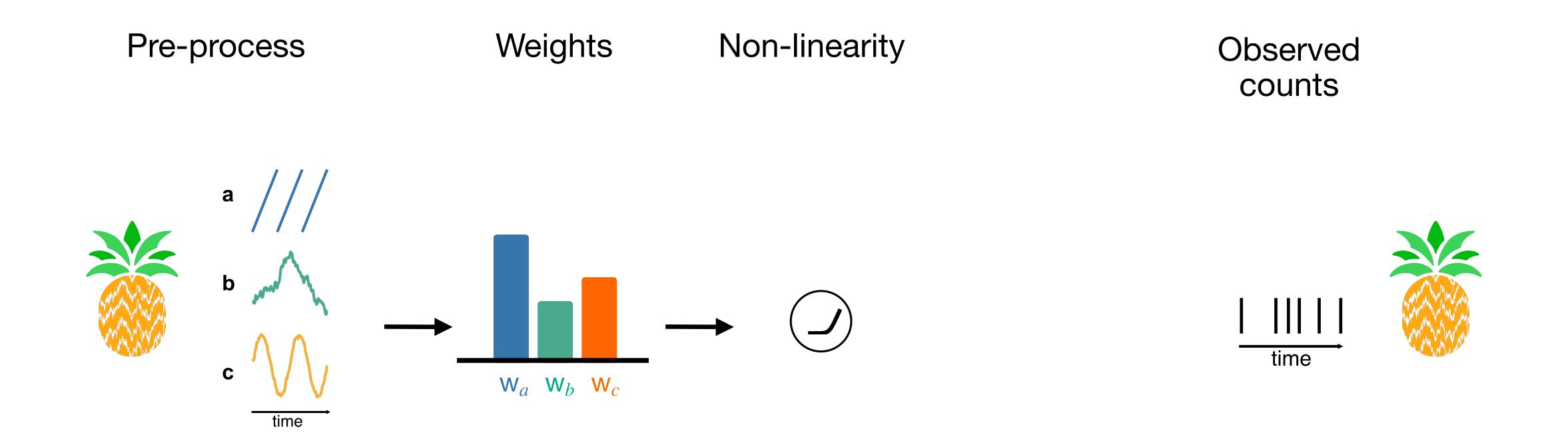


tuning functions don't tell you the whole story need better models!



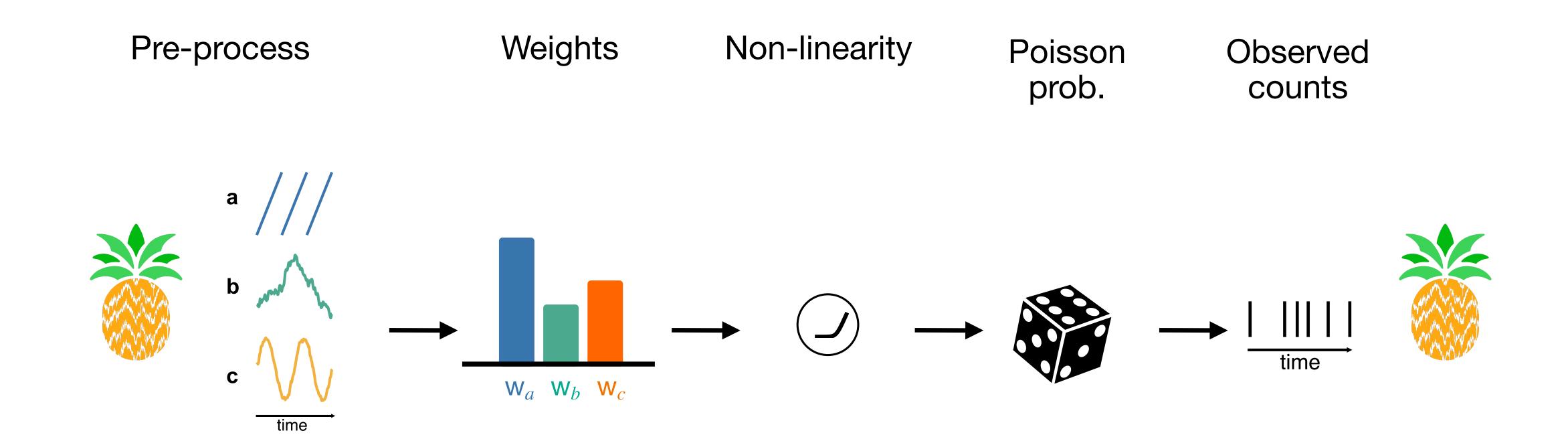
scale the inputs by some weights

$$\mathbf{a} \cdot \mathbf{w}_a + \mathbf{b} \cdot \mathbf{w}_b + \mathbf{c} \cdot \mathbf{w}_c$$



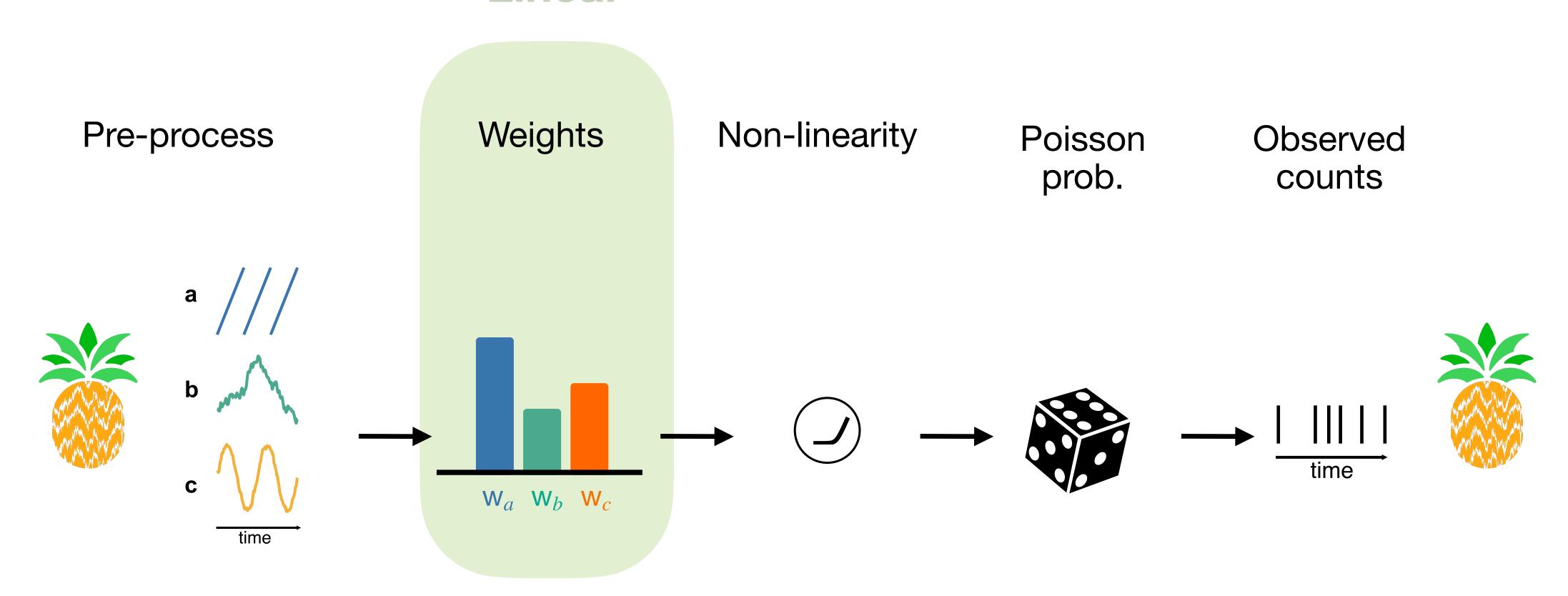
non-linearity to make the result positive

firing rate = exp(
$$\mathbf{a} \cdot \mathbf{w}_a + \mathbf{b} \cdot \mathbf{w}_b + \mathbf{c} \cdot \mathbf{w}_c$$
)



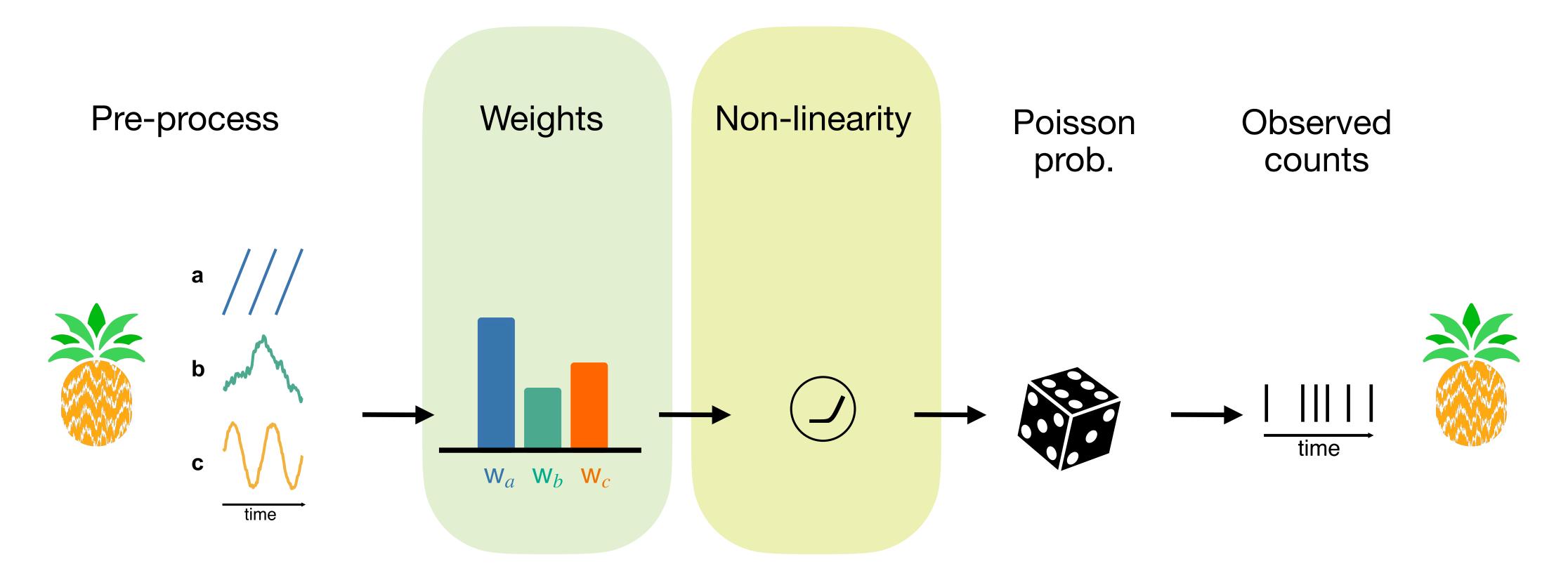
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#### Linear



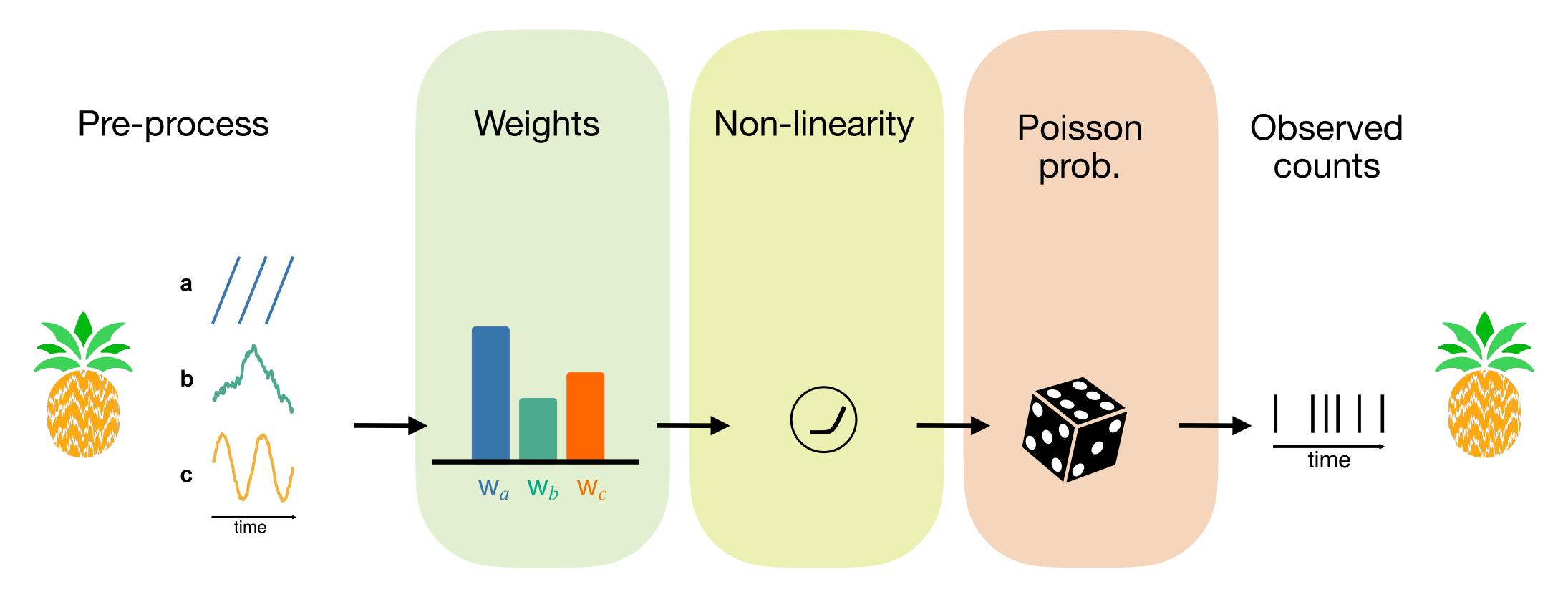
firing rate = exp(
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#### Linear - NonLinear

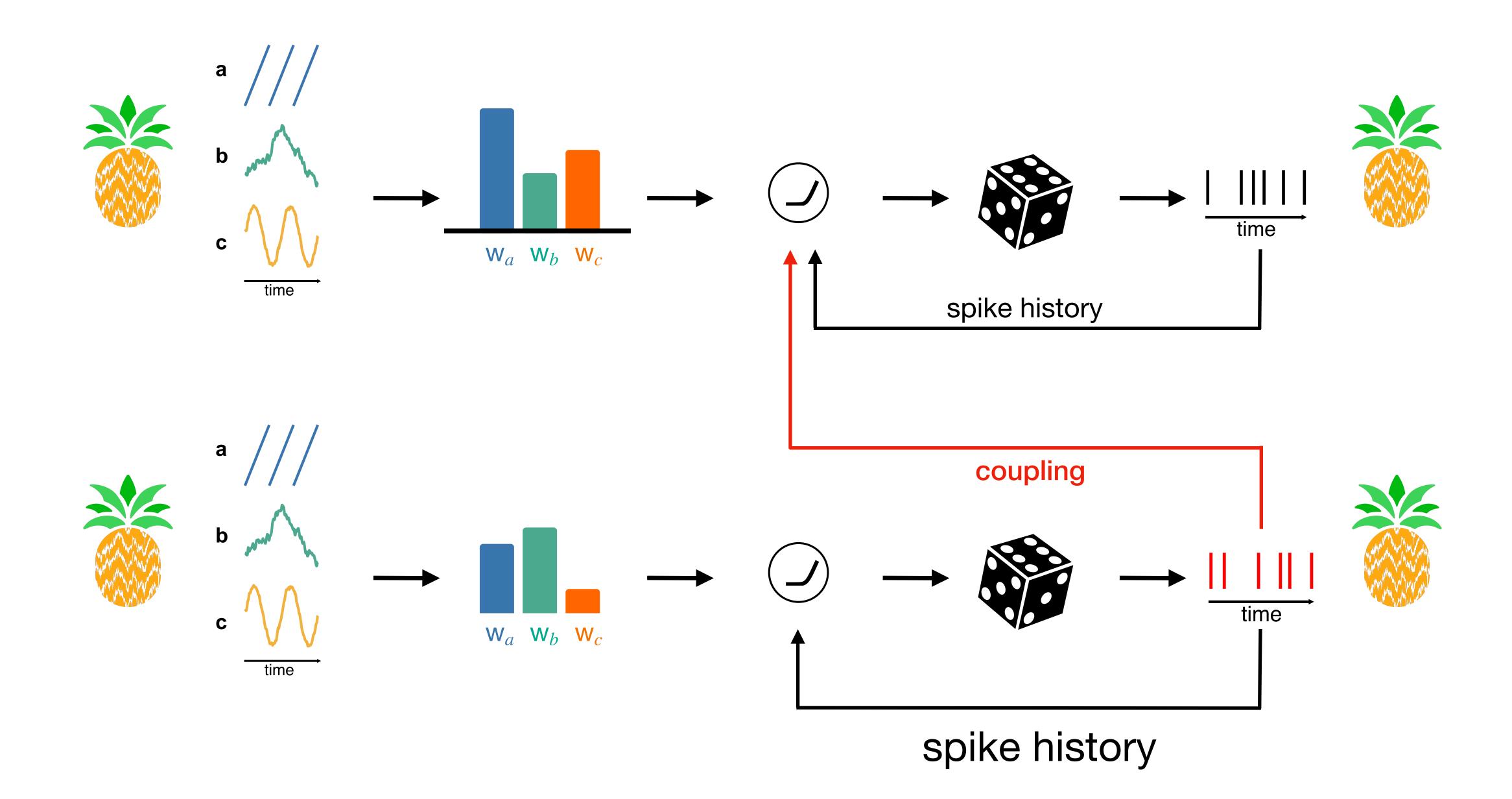


firing rate = exp(
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)

# Linear - NonLinear - Poisson (LNP)



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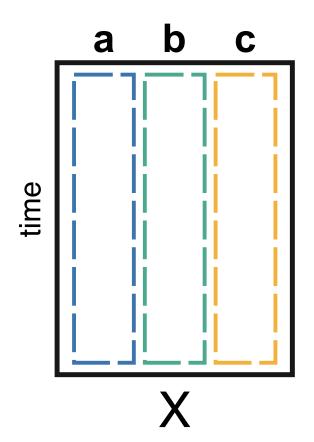
• a, b, c are called features or predictors

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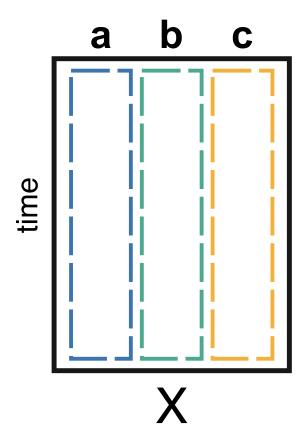
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- The **likelihood** is the probability of observing spike counts given some features and weights.

# **Design matrix**



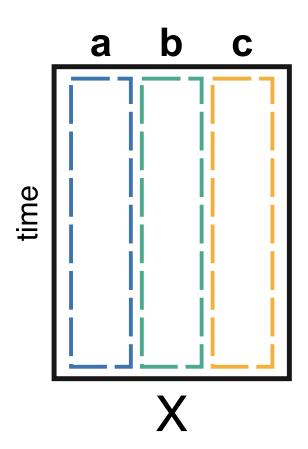
#### Likelihood

probability(spike count =  $k \mid \mathbf{X}, \mathbf{w}$ )

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$$\mathbf{a} \cdot \mathbf{w}_a + \mathbf{b} \cdot \mathbf{w}_b + \mathbf{c} \cdot \mathbf{w}_c$$
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- The **likelihood** is the probability of observing spike counts given some features and weights.
- The likelihood is a function of the weights because counts and features are fixed.

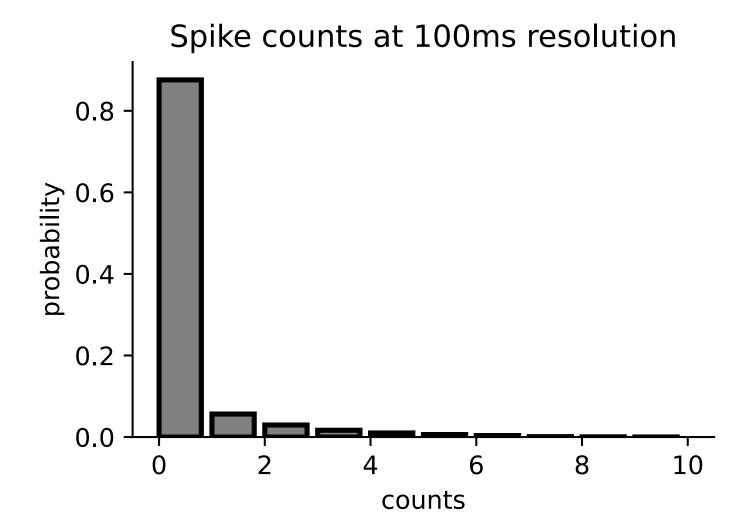
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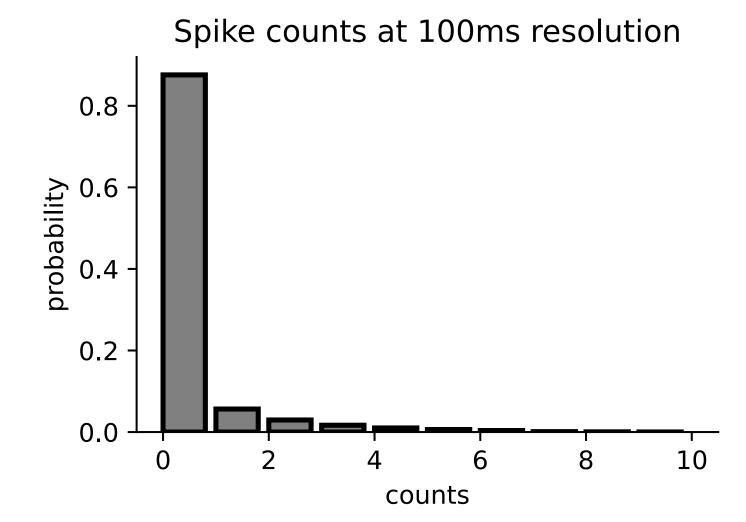
#### Likelihood

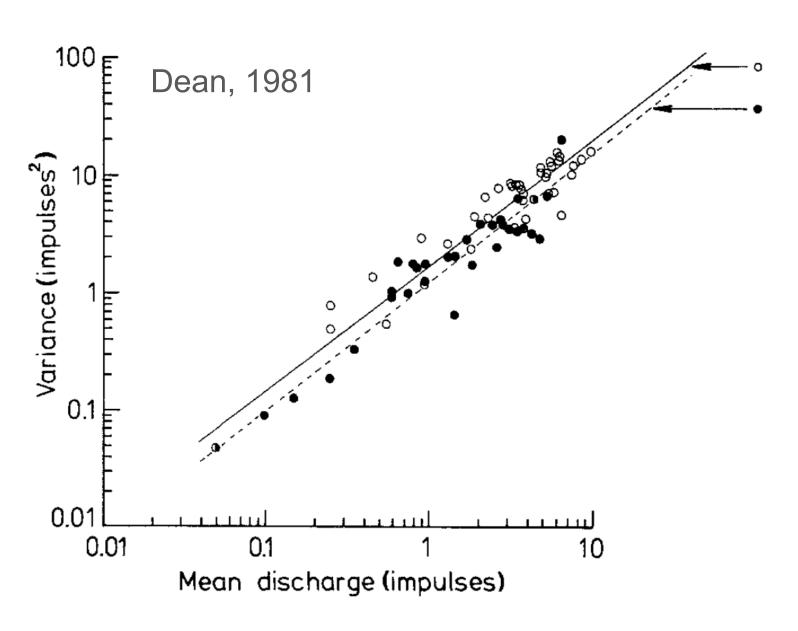
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- 1. Why not linear regression? which assumes normality
  - A. Spike counts are non-Gaussian

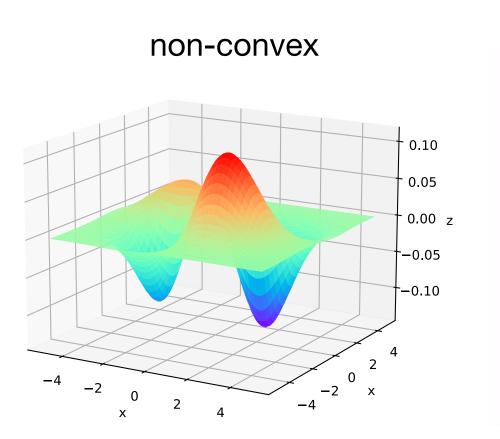


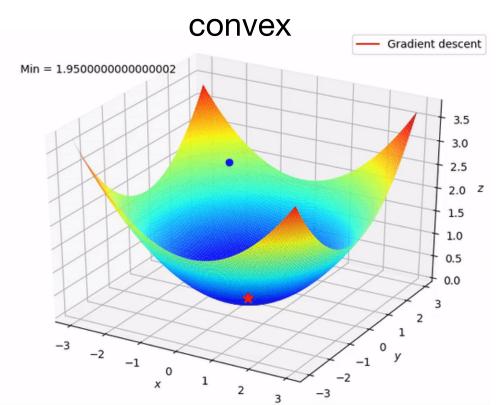
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  - B. Neural activity variance is non-constant



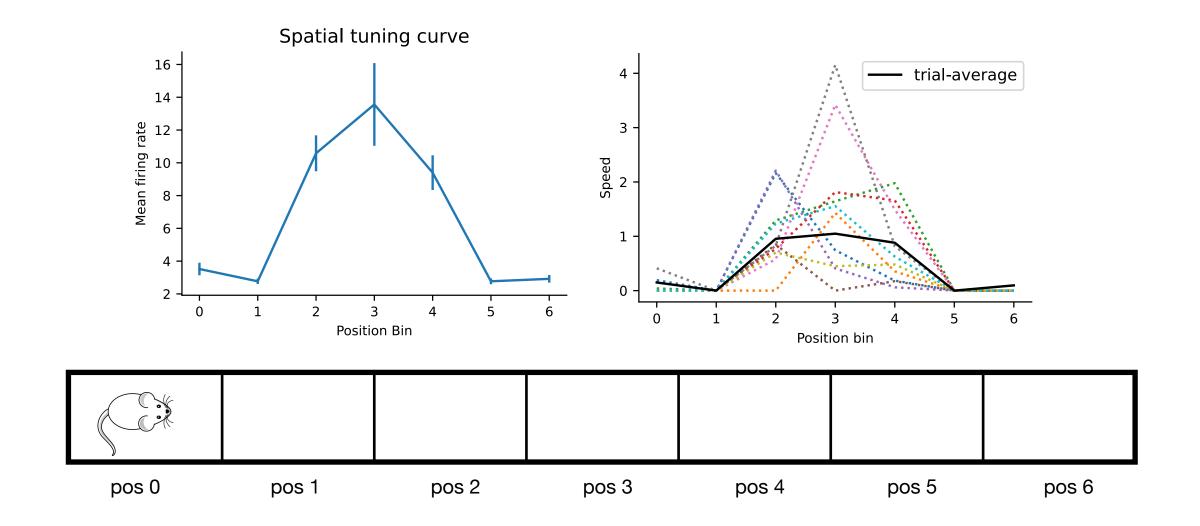


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- 2. GLM are as **easy to fit** as linear regression convex, unique optimal solution





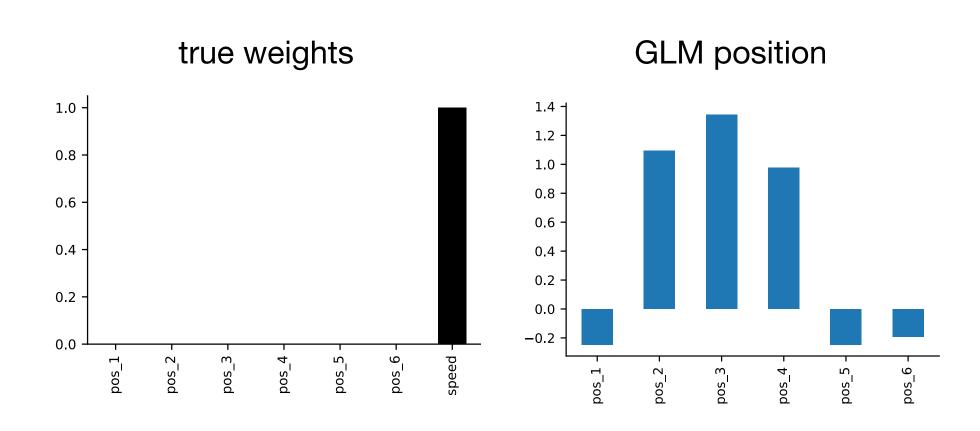
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- 3. GLM are **flexible** model multiple inputs jointly



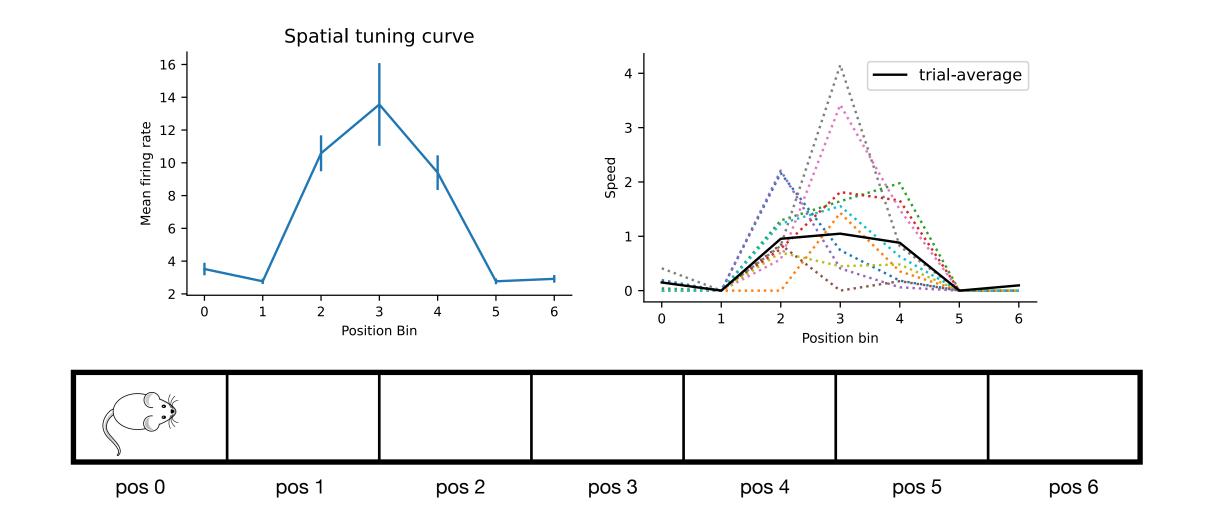
#### Firing rate model:

firing rate =  $\exp(w_0 \cdot pos_0(t) + ... + w_6 \cdot pos_6(t))$ 

 $pos_i(t) = \begin{cases} 1 & \text{if mouse is in position } i \text{ at time} t \\ 0 & \text{otherwise} \end{cases}$ 



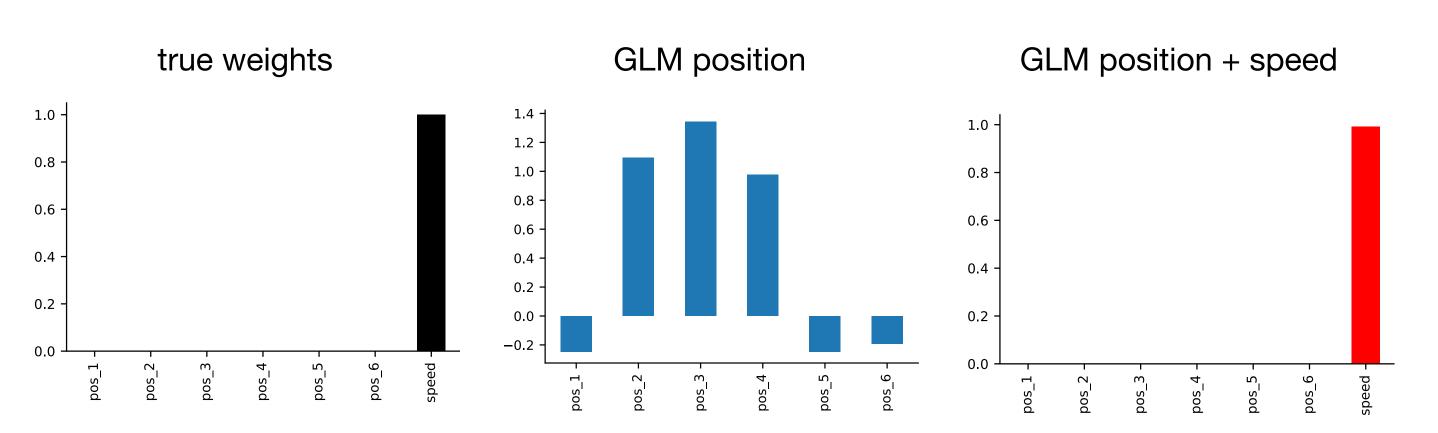
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firing rate =  $\exp(w_0 \cdot \text{pos}_0(t) + \dots + w_6 \cdot \text{pos}_6(t) + w_s \cdot \text{speed}(t))$ 

$$pos_i(t) = \begin{cases} 1 & \text{if mouse is in position } i \text{ at time } t \\ 0 & \text{otherwise} \end{cases}$$



1. Model responses to high dimensional inputs images, videos, 2D/3D positions...

Pillow at al., 2008
Retina Macaques

Hardcastle et al., 2018
MEC mice

Gardner et al. 2019 *MEC rats* 

Park et al. 2019 LIP Macaques

Weber & Pillow 2017 simulations

Peyrache et al., 2018 ADN mice

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2. Non-linear responses

place cells, head-direction, grid cells

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1. Model responses to high dimensional inputs images, videos, 2D/3D positions...

- 2. Non-linear responses place cells, head-direction, grid cells
- 3. Functional connectivity and other time-dependent effects

Pillow at al., 2008
Retina Macaques

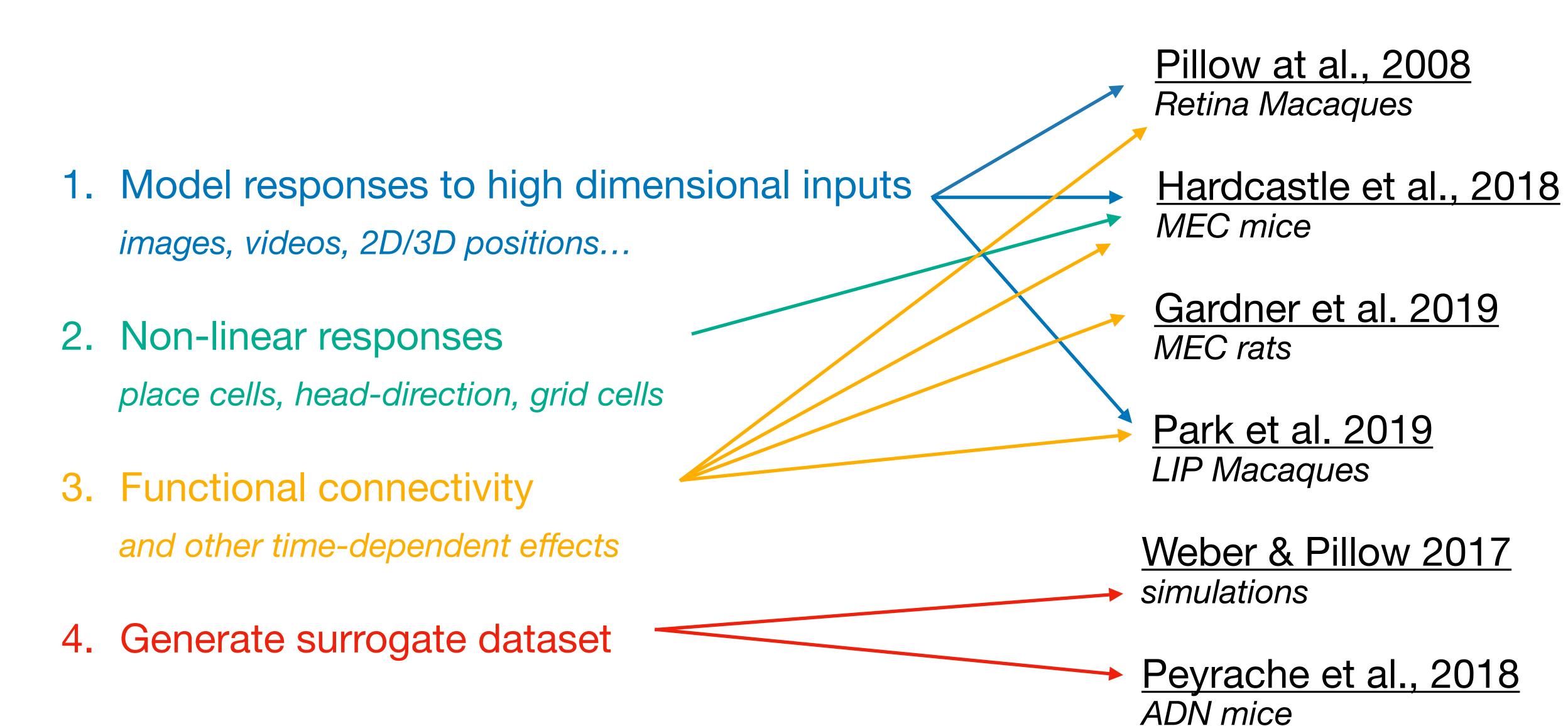
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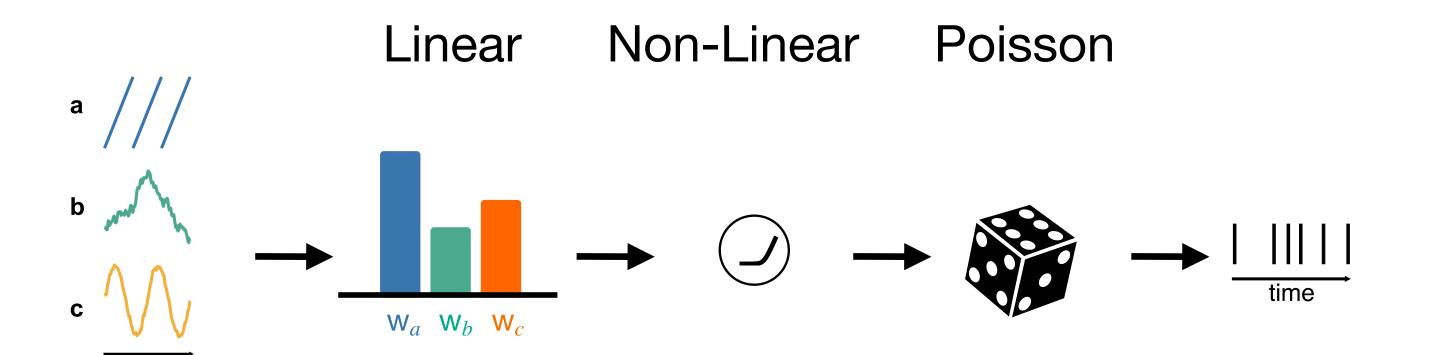
Gardner et al. 2019 MEC rats

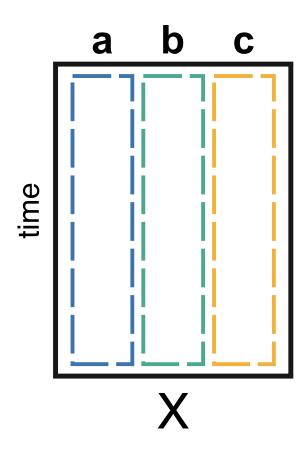
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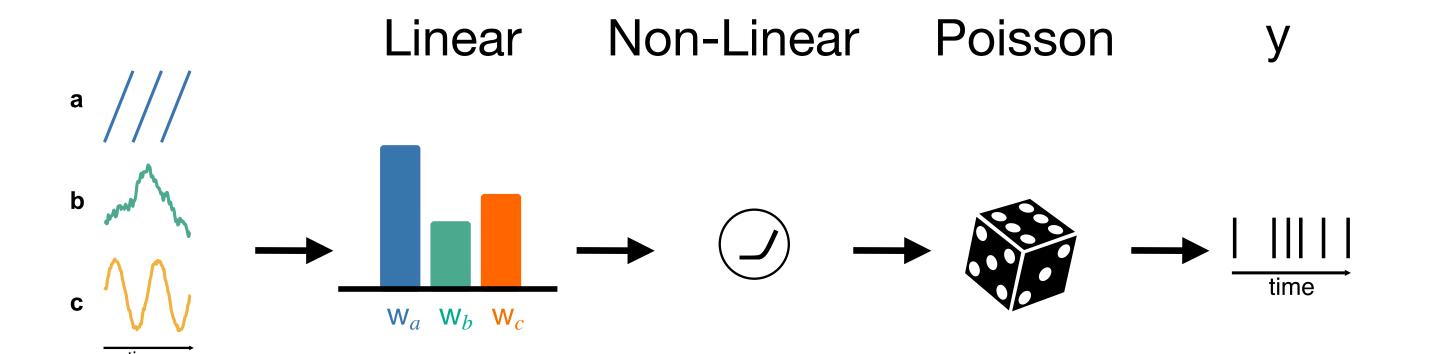
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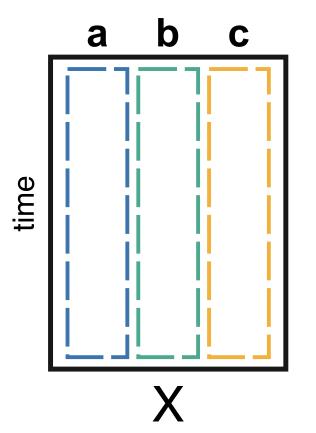






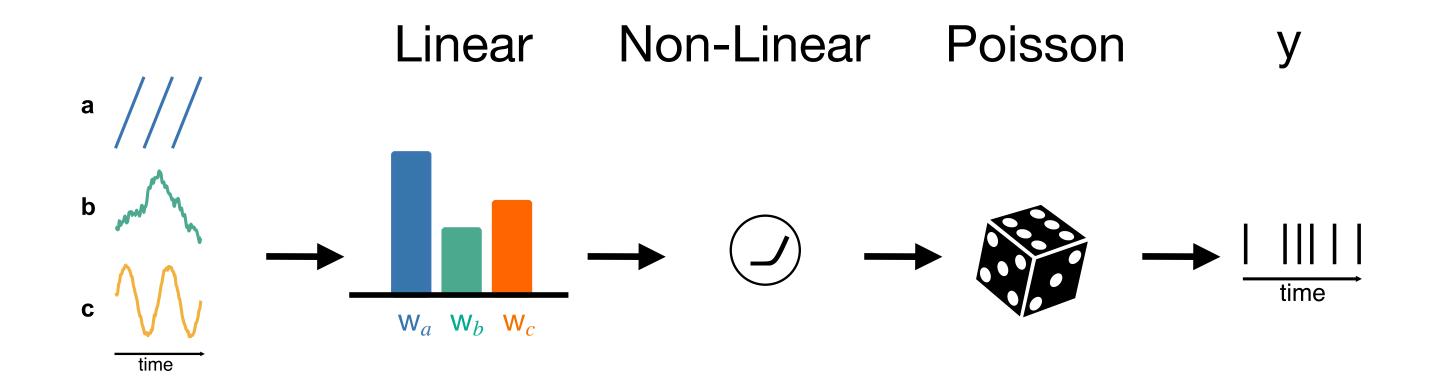
## **Feature matrix**

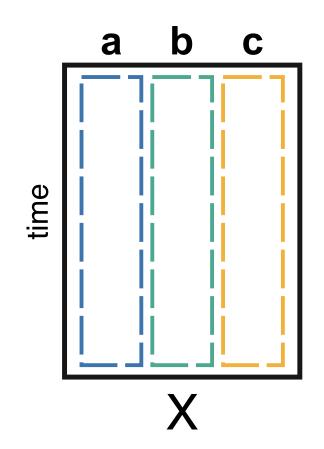


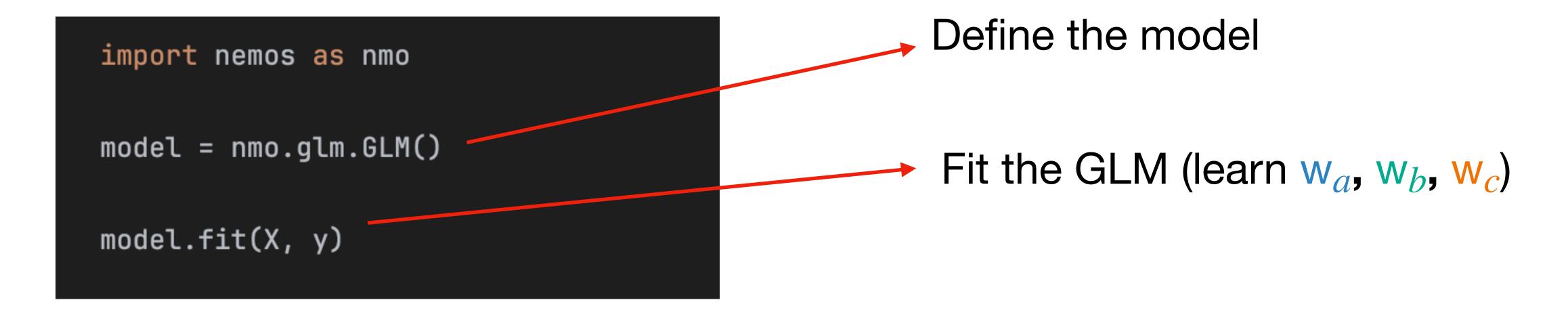


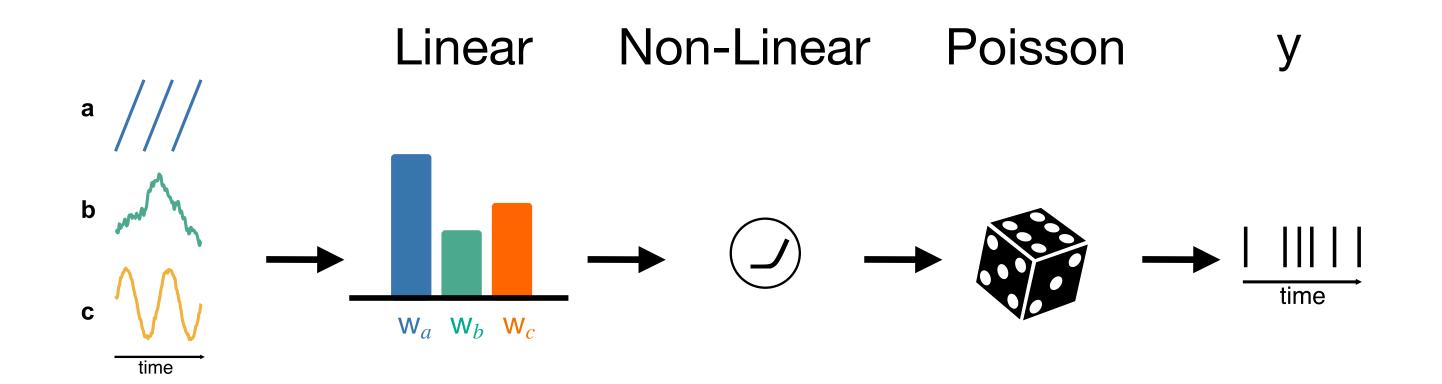
import nemos as nmo

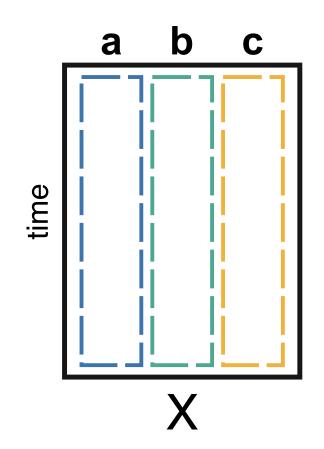
model = nmo.glm.GLM()
Define the model

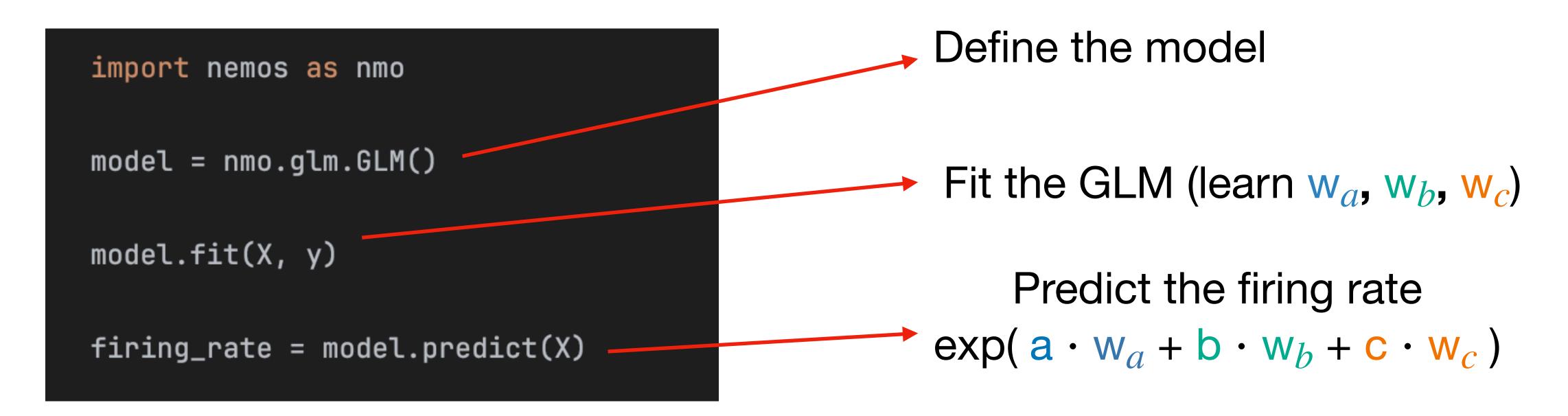


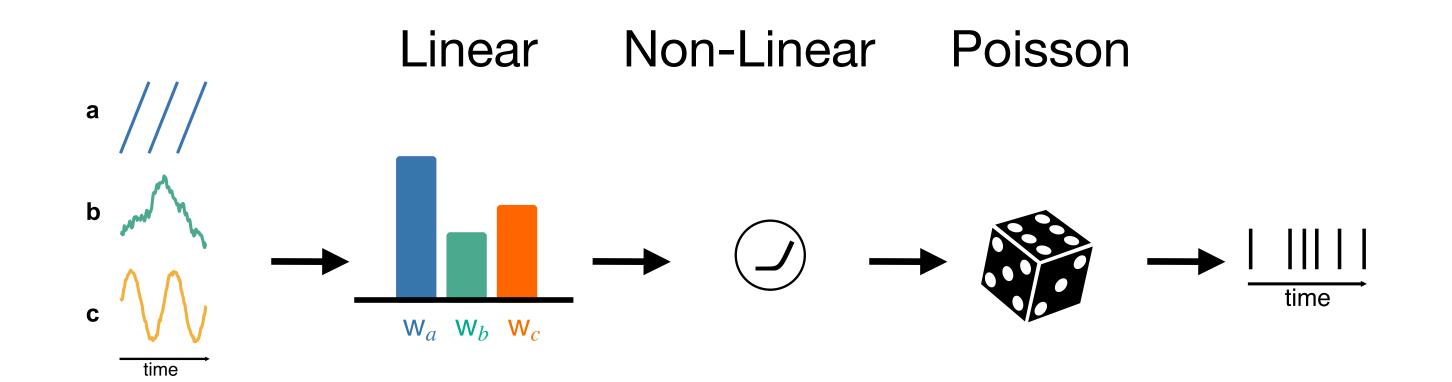


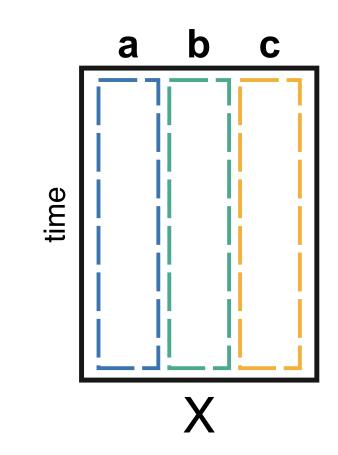


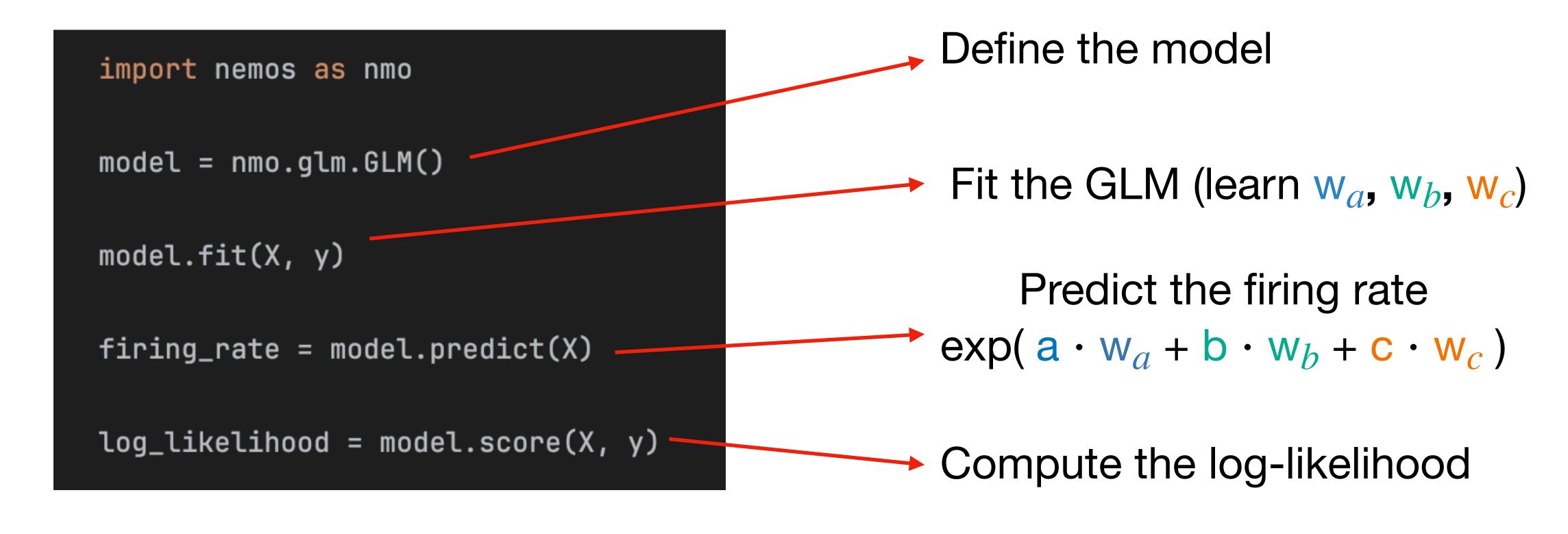












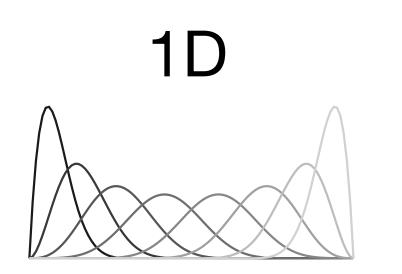
What features can/should I use?

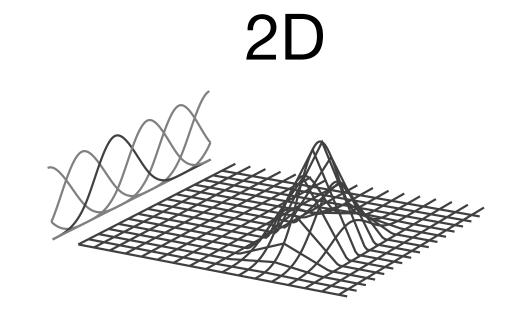
- It's up to the scientist!
- Choosing features is a way to formulate hypothesis about the neural encoding.
- Any fixed (not learned) transformation of your data is valid\* (counting, binning, projecting into Principal Components, filtering, squaring ...)

<sup>\*</sup>as long as the resulting time axis matches that of the spike counts

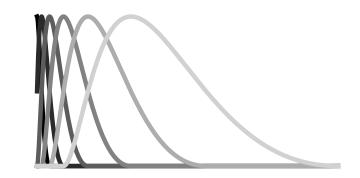
NeMoS provides the basis module for feature construction

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- Basis are fixed non-linearities

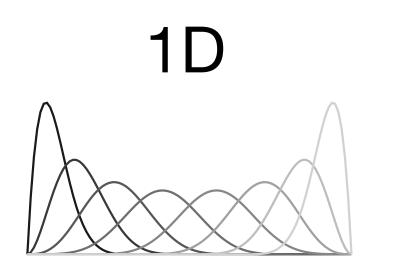


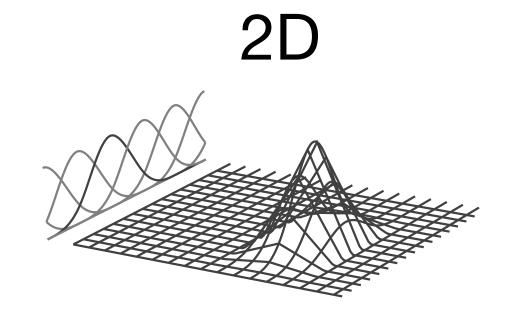


log-stretched

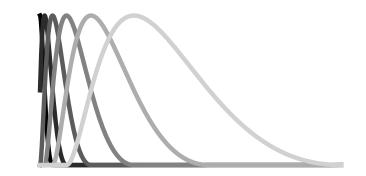


- NeMoS provides the basis module for feature construction
- Basis are fixed non-linearities
- Assume that firing rate varies smoothly/ gradually

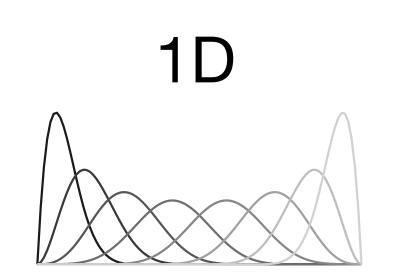


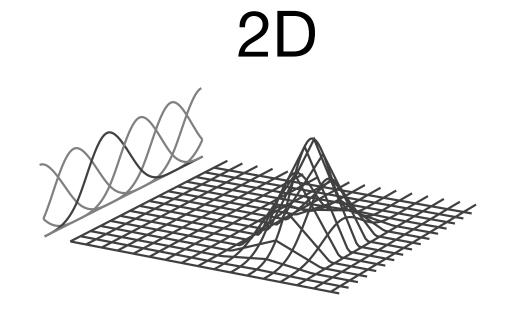


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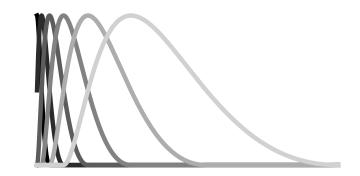


- NeMoS provides the basis module for feature construction
- Basis are fixed non-linearities
- Assume that firing rate varies smoothly/ gradually
- Used for:
  - 1. Reducing dimensionality
  - 2. Non-linear firing rate modulation
  - 3. Time dependent effects

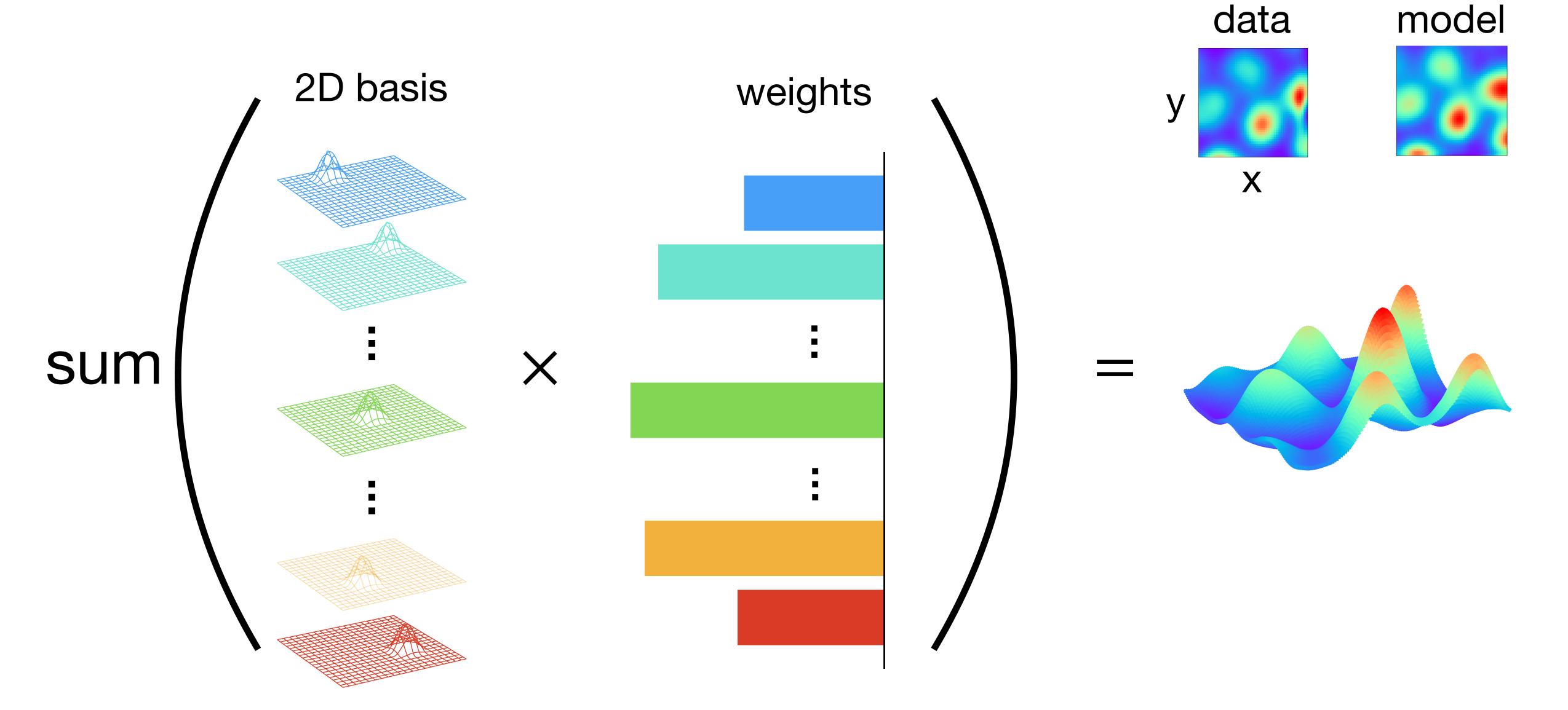


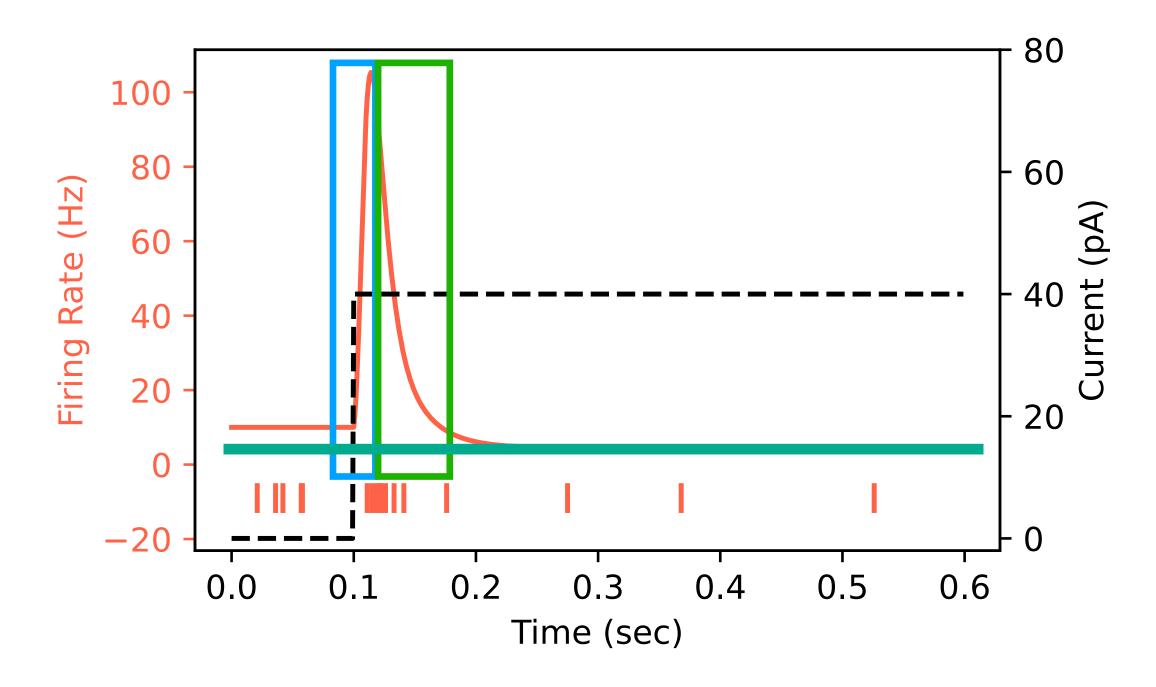


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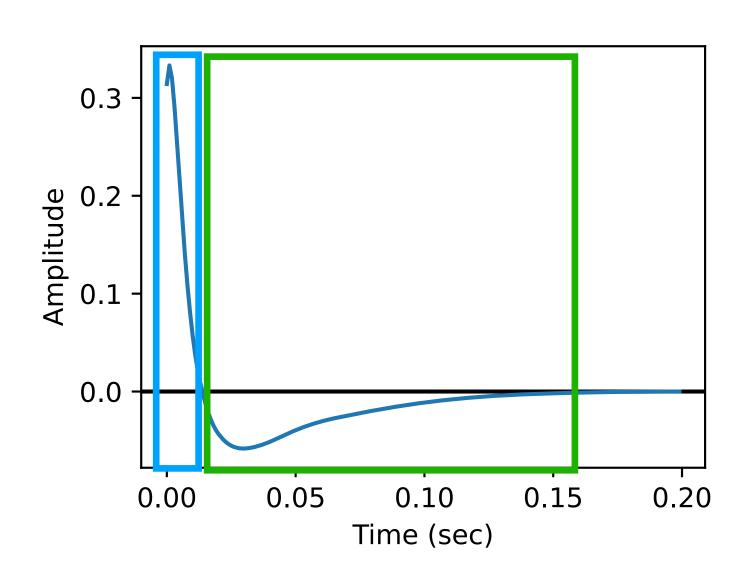
# Example: Non-Linear Rate Map





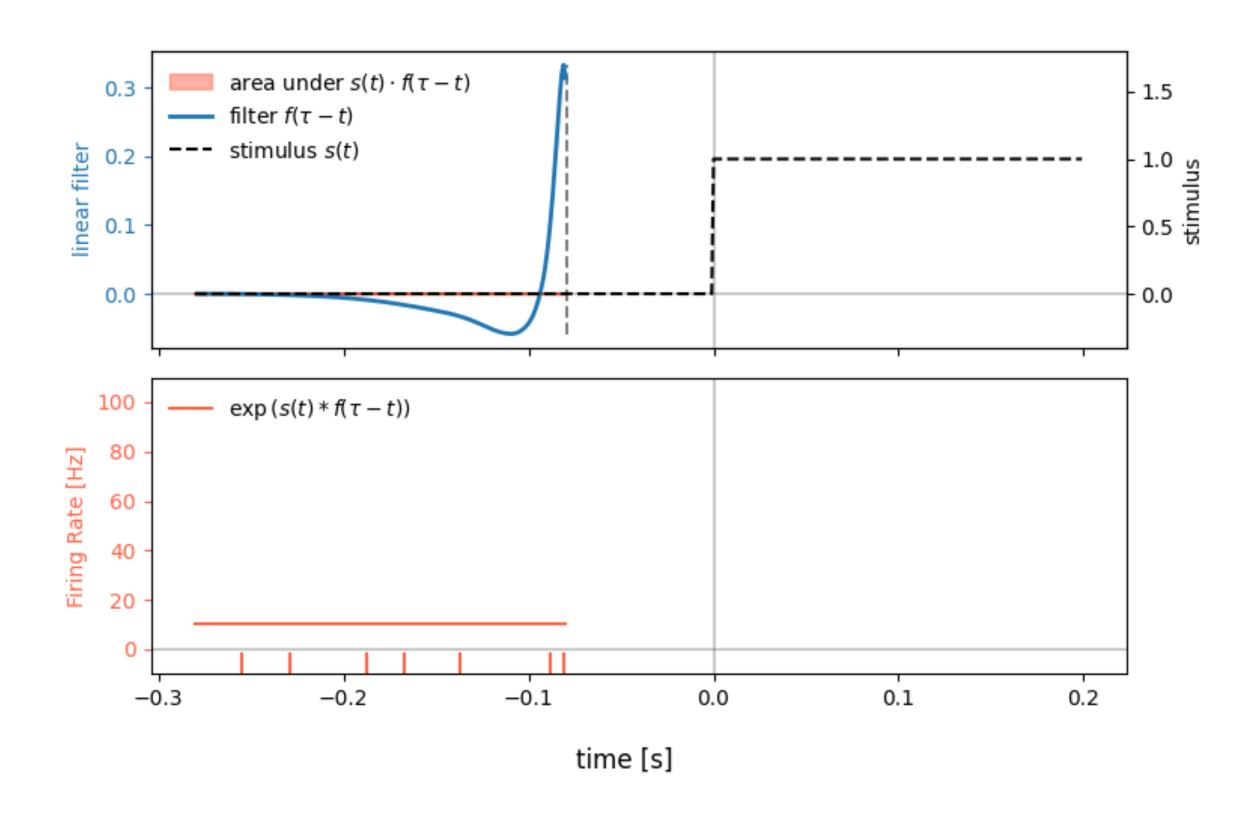
Input: constant current

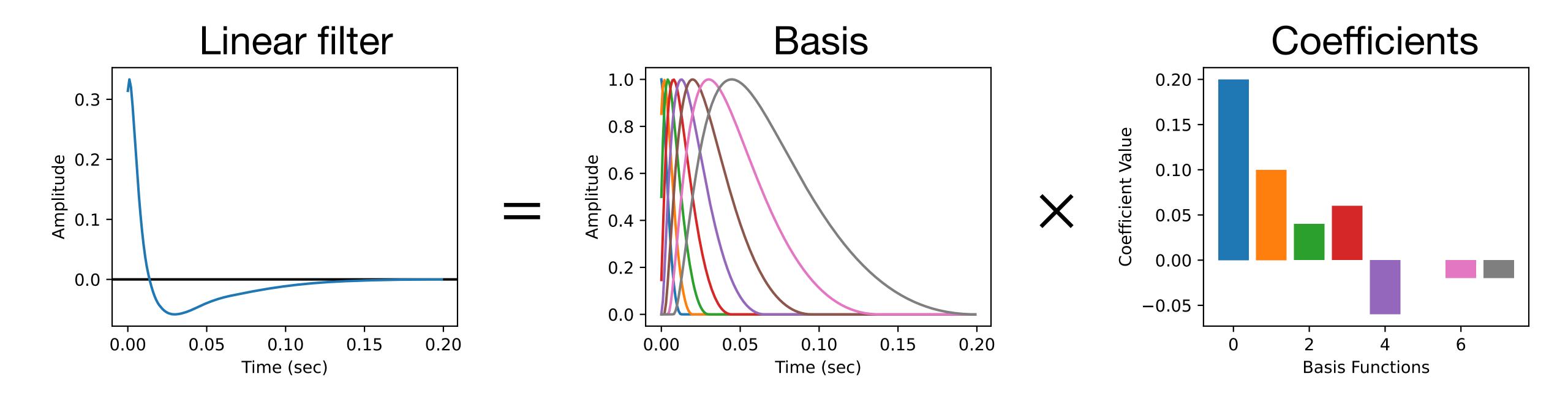




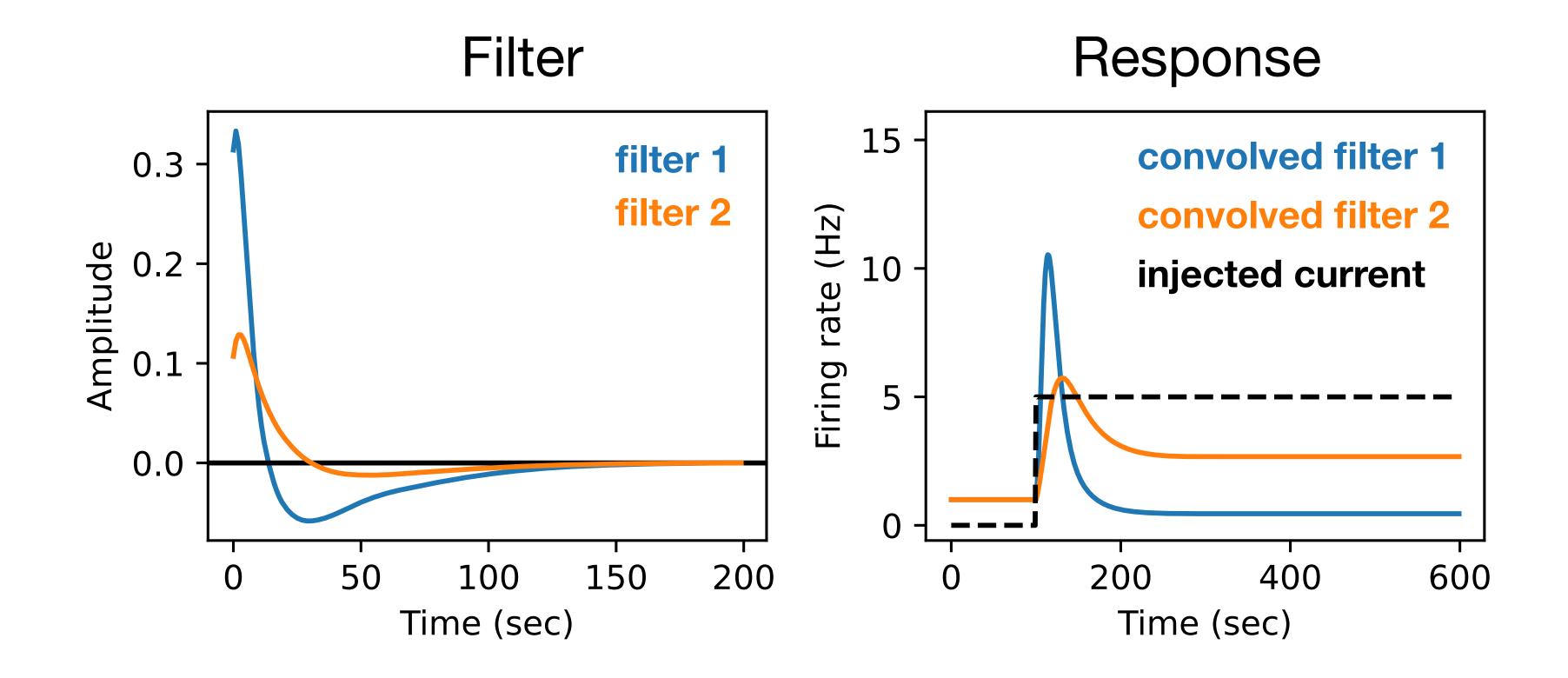
Response to a current impulse

# Linear filter convolved with the current + non linearity





- 1ms resolution, for 200ms window => 200 numbers to describe the filter
- With basis you need only 8 numbers



Many different responses can be captured by a linear filter

# Why NeMoS?

### 1. Pynapple support:

- Carry over time information (and metadata)
- Handle disjoint epochs avoiding border artifacts

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Raised Cosine basis, population GLMs, simplified model design

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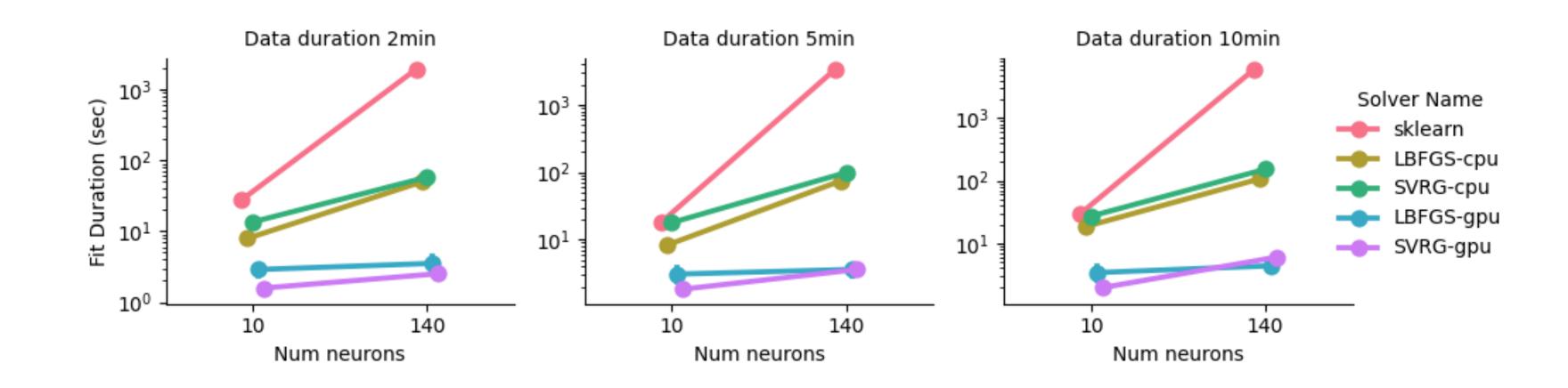
### 1. Pynapple support:

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### 3. Performance (GPU)



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- GLMs retain many of the advantageous properties of linear regression (easy to fit, unique solution)
- Better suited for non-normally distributed data.
- Rich framework: model jointly many features, flexible design...

## Today's roadmap

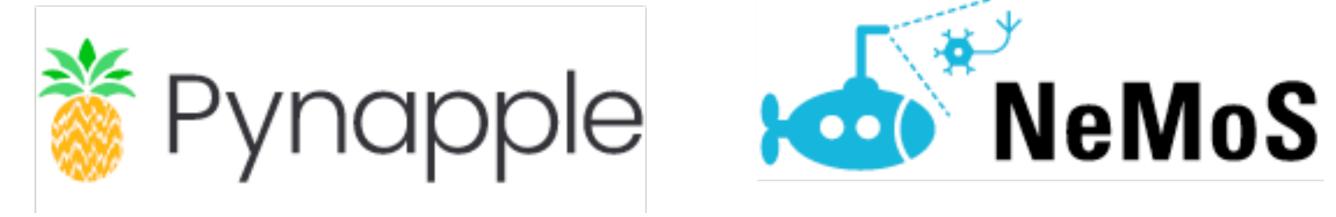
#### Current injection live coding:

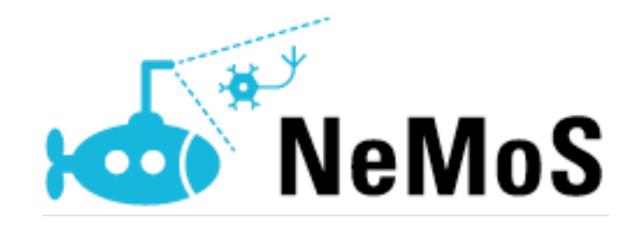
- Load and explore a intracellular recordings from the Allen Brain Map with pynapple.
- Fit an LNP model to a single input.
- Capture temporal effects using NeMoS' basis.

#### Group Projects: Analyze Head direction cells

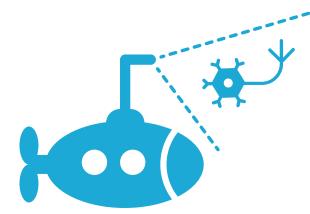
- Population head direction tuning properties
- Compare activity during sleep and wake via cross-correlograms
- Capture spike history effects with a recurrently connected GLM.
- Infer functional connectivity with a coupled GLM.







#### **Documentation Website**



https://nemos.readthedocs.io/en/stable/



https://pynapple.org/



@nemos\_neuro

@thepynapple